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(54) **TRANSPARENT MULTI-ZONE CRYSTAL GROWTH FURNACE AND METHOD FOR CONTROLLING THE SAME**

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(75) Inventors: **Walter Duval**, Lakewood; **Celal Batur**, Fairlawn; **Robert J. Bennett**, Birmingham, all of OH (US)

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(73) Assignees: **The University of Akron and Nasa**;  
**The United States of America**

*Primary Examiner*—Felisa Garrett

(74) *Attorney, Agent, or Firm*—Renner, Kenner, Greive, Bobak, Taylor & Weber

(\*) Notice: Under 35 U.S.C. 154(b), the term of this patent shall be extended for 0 days.

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**Related U.S. Application Data**

(62) Division of application No. 09/157,820, filed on Sep. 21, 1998, now abandoned.

(51) **Int. Cl.**<sup>7</sup> ..... **C30B 15/20**

(52) **U.S. Cl.** ..... **117/14; 117/15**

(58) **Field of Search** ..... 117/14, 15

(56) **References Cited**

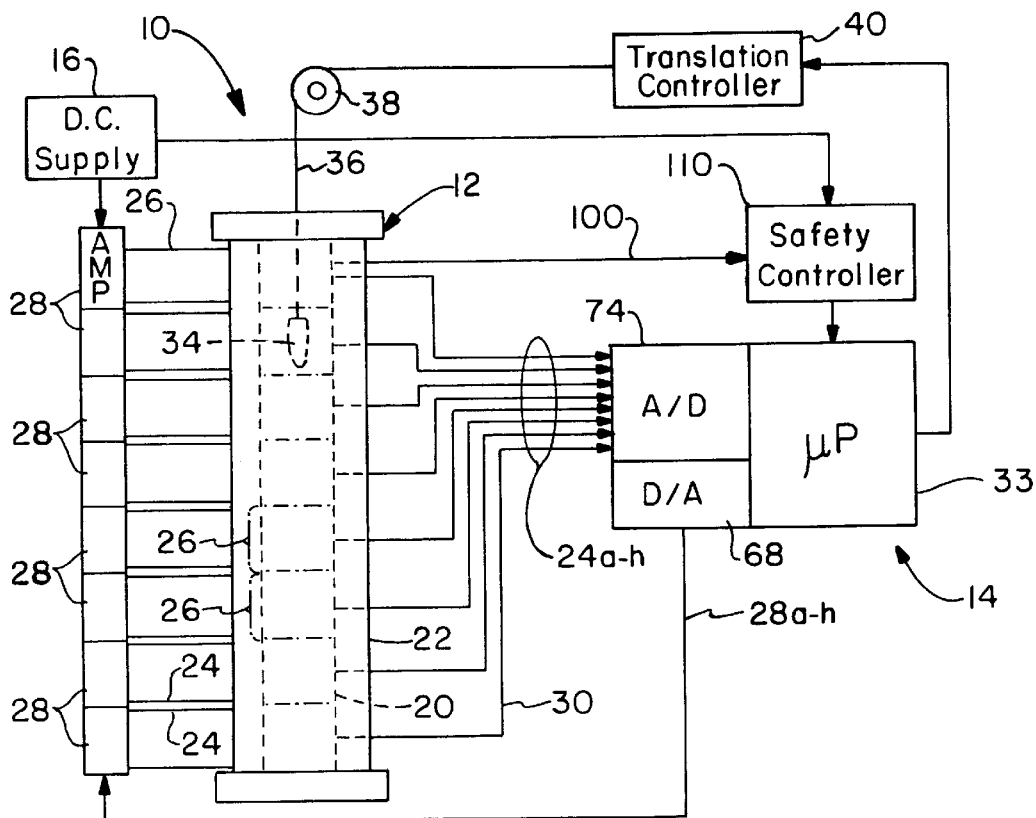
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(57) **ABSTRACT**

A crystal growth system, comprising: a furnace; a plurality of heating elements coupled to said furnace, each said plurality of heating elements defining a heat zone, each said heating element set to a desired temperature value; a plurality of thermocouples associated with respective heat zones to detect a temperature value; a translation system for passing an ampoule containing crystal growth material through said furnace into said heat zones and providing a positional location of said ampoule and; a multi-variable self-tuning temperature controller connected to said plurality of heating elements, said plurality of thermocouples and said translation system, said controller monitoring each said zone temperature value and upon considering the thermal interaction of heating zones and the moving thermal inertia of the ampoule, adjusting voltage input to said heat zones to obtain optimal crystal growth within said ampoule.

**15 Claims, 4 Drawing Sheets**



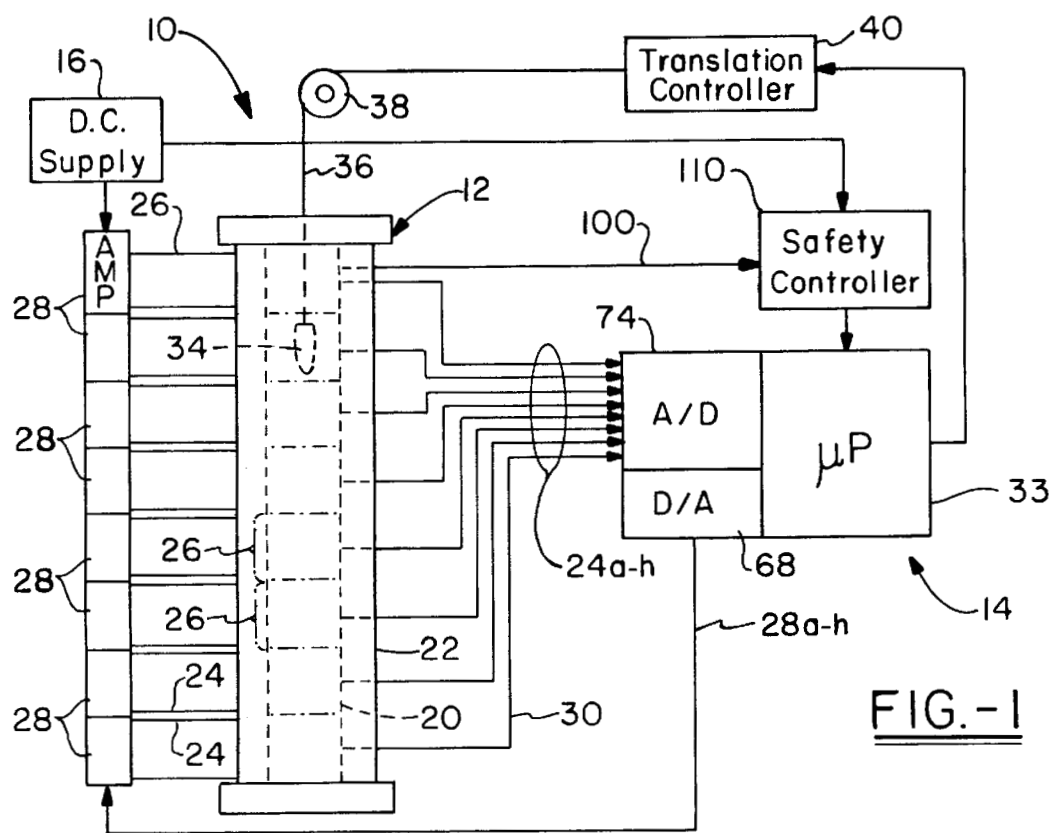


FIG. -1

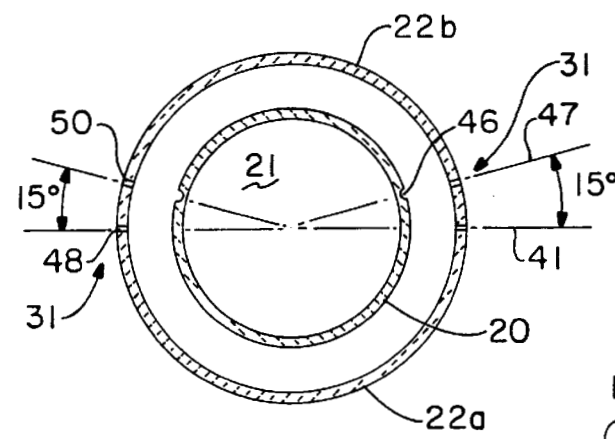


FIG. -3

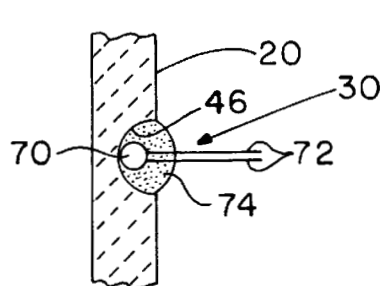


FIG. -4A

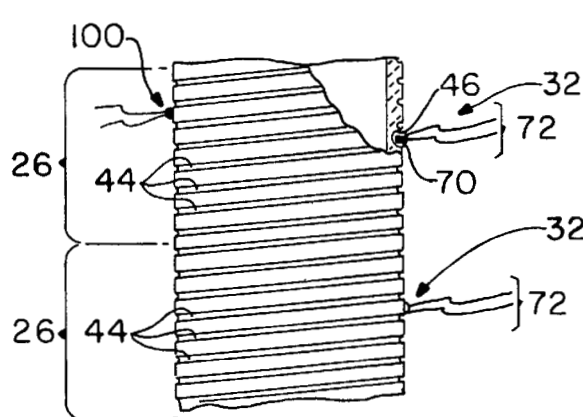


FIG. -4

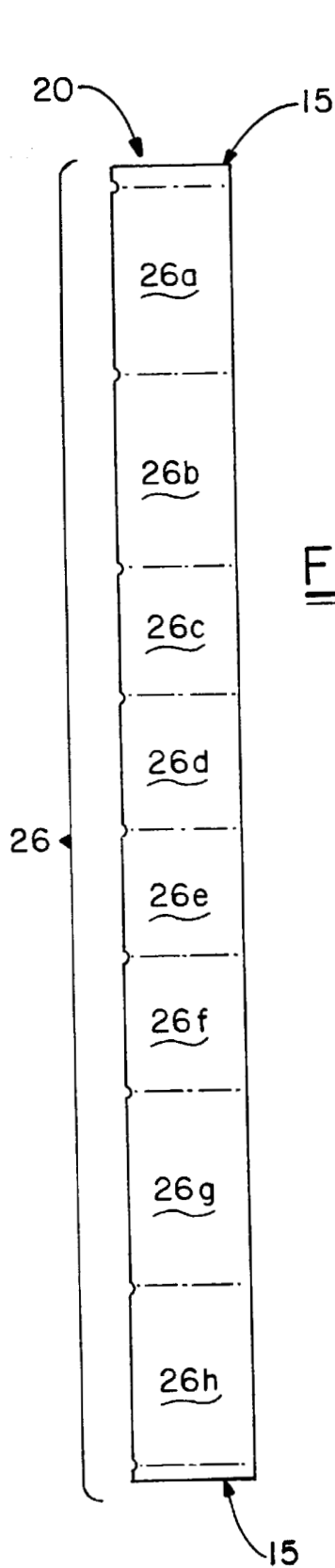
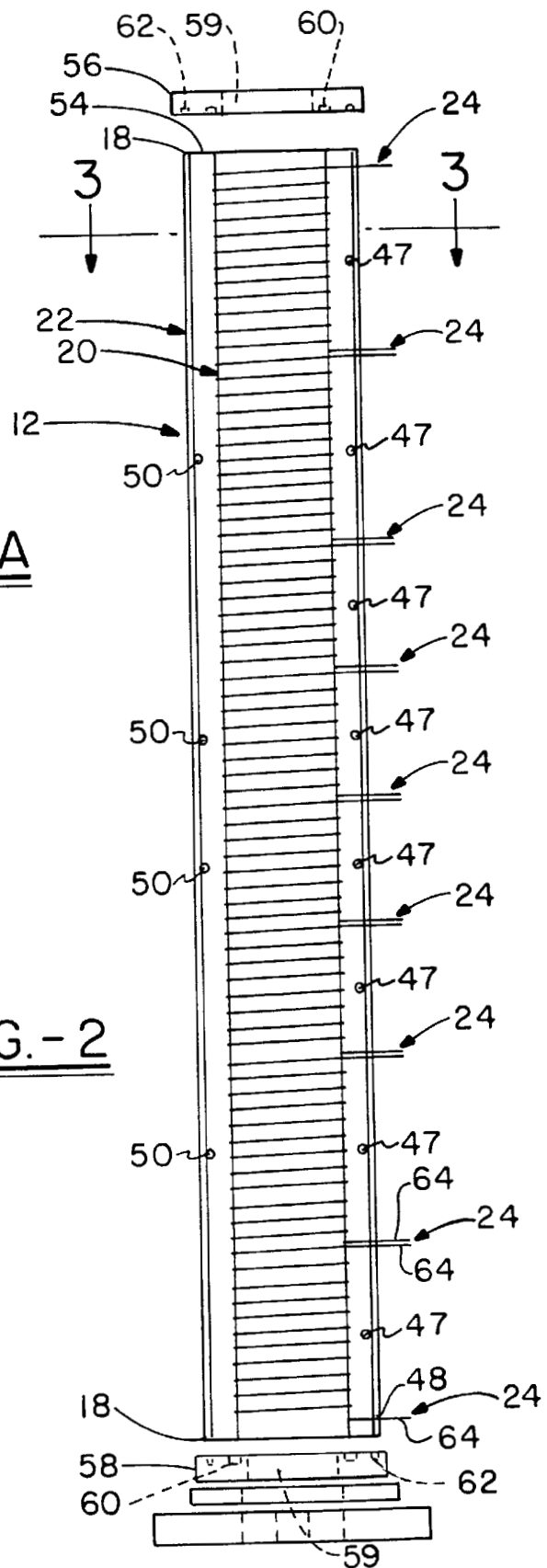
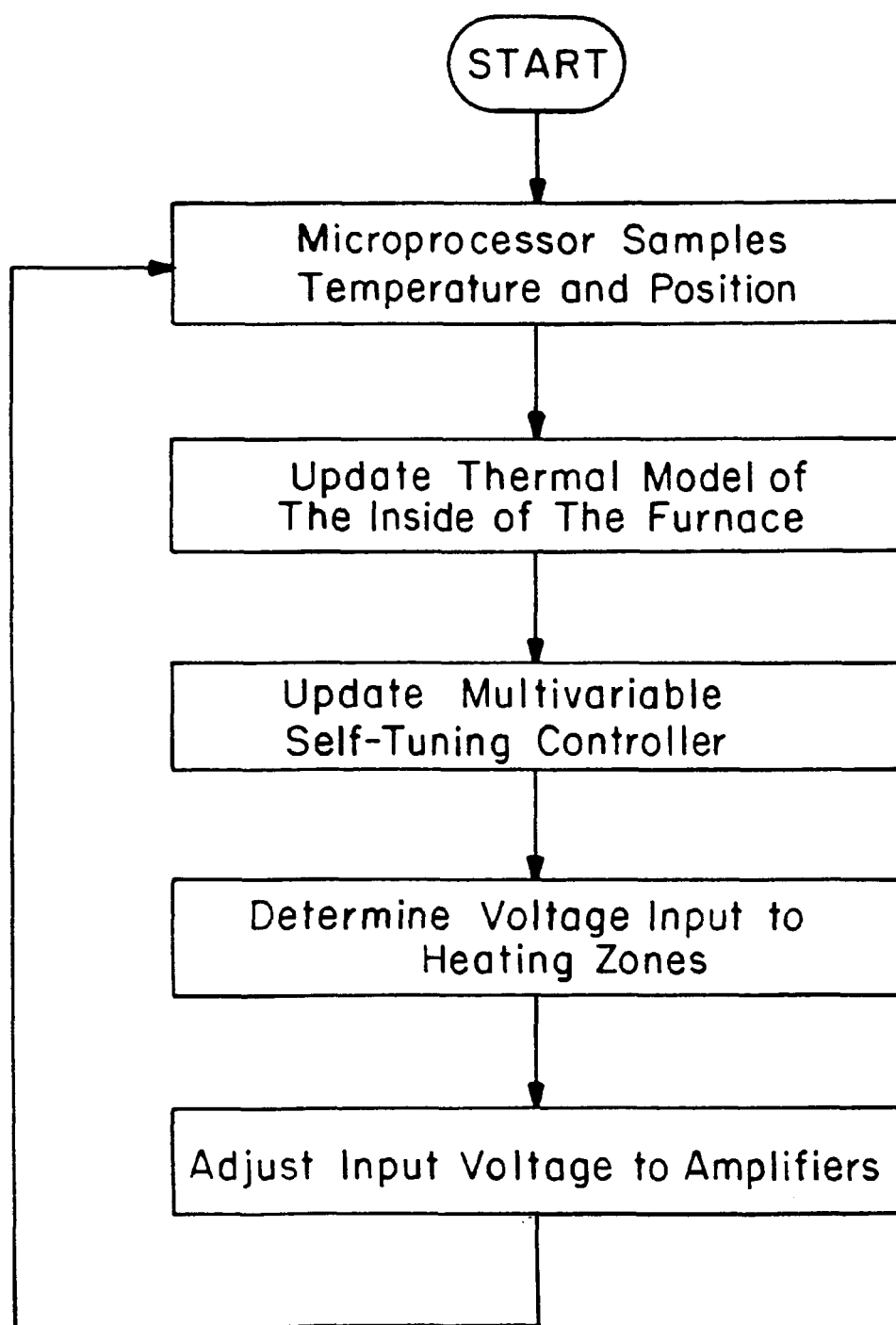


FIG. -1A

FIG. -2



FIG.-5

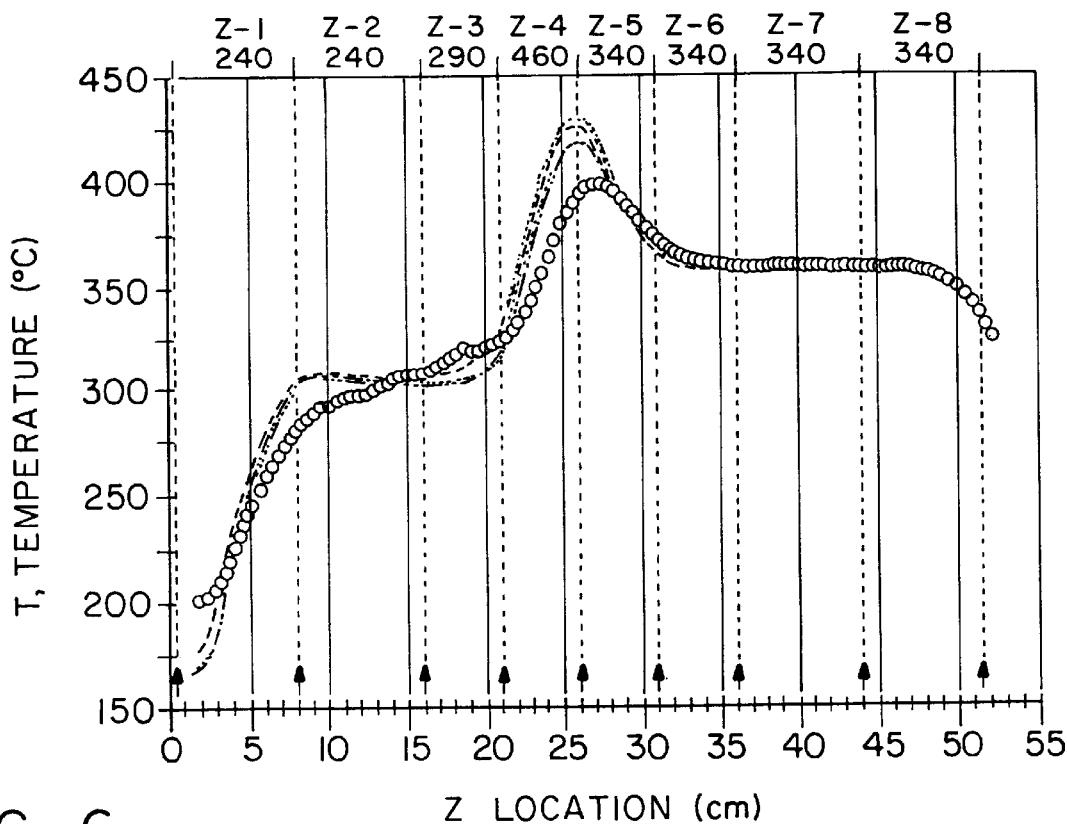


FIG.-6

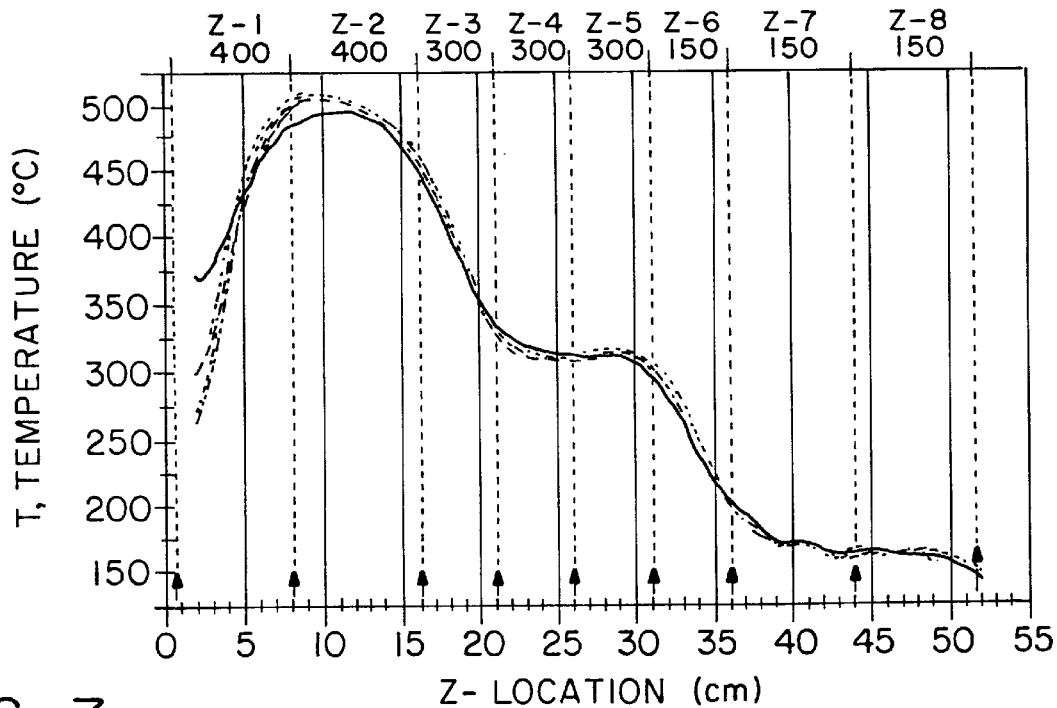


FIG.-7

# TRANSPARENT MULTI-ZONE CRYSTAL GROWTH FURNACE AND METHOD FOR CONTROLLING THE SAME

This application is a division of application Ser. No. 09/157,820, filed Sep. 21, 1998 now abandoned.

## GOVERNMENTAL RIGHTS

The U.S. Government has a paid-up license in this invention and may have the right in limited circumstances to require the patent owner to license others on reasonable terms as provided for by the terms of Grant No. NCC 3-567 awarded by NASA.

## TECHNICAL FIELD

The present invention relates generally to crystal growth furnaces and in particular to a vertical multi-zone transparent crystal growth furnace. More specifically, the present invention is directed toward a self-tuning furnace that accounts for zone to zone thermal interactions.

## BACKGROUND OF THE INVENTION

Lead bromide crystals are used to produce an acousto-optical tunable filter of very high optical quality. These crystals are used to filter laser light waves that pass there-through without distortion. Any non-homogeneity severely diminishes the effectiveness of such a crystal.

In a crystal growth furnace, materials are placed in an ampoule heated until liquified and cooled under controlled conditions allowing a crystal to grow. Careful control of the heating and cooling conditions improves the quality of the crystal. The crystals begin to form at a solidification point during the growth process. At this point an interface exists between the liquid material and the crystallized material. The shape of the interface is directly related to the quality of the crystal formed. The most preferable shape is a flat surface (flat interface) between the liquid and solid phases. A flat interface indicates a crystal free of impurities and defects in its structure. Convex and concave shapes indicate the likelihood of thermal stresses which can decrease the quality of crystal.

Traditionally, a two zone Bridgman type furnace is used for lead bromide crystal growth. To achieve requisite crystal homogeneity, for the acousto-optical tunable filter application, the crystal growth must exhibit a flat interface between the solid and liquid phases. The Bridgman furnace is a vertical furnace with a hot and cold zone. The hot and cold zones create a thermal gradient therebetween. Insulation is used in traditional designs in and around the furnace maintaining axial heat flow to create a nearly-flat interface. The presence of insulation prevents observation of the interface and adjustment of the thermal characteristics of the furnace to compensate for any change in the interface shape. Thus, the traditional Bridgman furnace lacks the versatility for optimal control of crystal growth parameters necessary for producing crystals of sufficient quality for acousto-optical tunable filters.

Visual monitoring of the interface is important for commercial applications and as a research tool to study interface dynamics. Visual monitoring allows the observer to adjust the thermal profile inside the furnace in order to insure high quality crystals. Also, for educational purposes, observation of the crystal as it is formed allows students to observe the relation between the thermal conditions within the furnace and the interface shape.

Multiple-zone furnaces can be used to create individual heat zones capable of controlling the growth of the crystal without using insulation between the zones. It is known to use proportional, integral, derivative controllers to regulate the temperature at each zone. Proportional, integral, derivative control cannot account for zone to zone thermal interaction and the thermal inertia of the ampoule as it translates through the furnace. Traditionally, multiple zone furnaces have failed to provide a controller that accounts for these thermal interactions and thus, the parameters to grow crystals were severely limited. Thus it is desirable to have a system that will precisely control the zone temperatures accounting for zone to zone thermal interactions and the thermal inertia of the ampoule.

Crystal growth is generally performed by moving an ampoule containing the crystal growth material physically through the hot and cold zones. Crystal quality and interface shape can be affected by any disruption of the movement of the ampoule through the heating zones. The crystal growth process requires the ampoule move at an extremely slow pace through the furnace. At times, the growth process can take up to a week or more. It is known to use stepper motors to control the translation of the ampoule. The stepper motor allows very slow translation through the heat zones, but produces a jerky motion of the ampoule. The jerks created by a stepper motor are detrimental to the quality of the crystal produced for extremely slow translation rates. Thus it is desirable to use a translation system that provides slow continuous (jerk free) motion.

The rate of translation through the zones can affect the growth rate and interface quality of the crystal. To control the growth rate and interface quality, it is desirable to control translation in response to changes in the thermal dynamics within the furnace.

To avoid moving the ampoule through the heat zones physically, it is possible to create an electro dynamic gradient. In effect, the electro dynamic gradient moves the thermal profile past the ampoule without having to move the ampoule physically. Multiple zone furnaces are capable of this effect. However, moving the heat zones increases the zone to zone heat interaction in the furnace. Traditional furnaces do not account for these interactions and the crystal quality suffers. It is desirable to create a crystal growth system accounting for the zone to zone thermal interactions to produce high quality crystals by means of electro dynamic gradient.

Thus, it is desirable to construct a crystal growth furnace that provides for visual inspection and precise control of the thermal gradient accounting for zone to zone thermal interactions and thermal inertia created by the ampoule.

## SUMMARY OF THE INVENTION

It is thus an object of the present invention to provide a multi-zone transparent crystal growth furnace that accounts for zone to zone thermal interaction and thermal inertia created by ampoule movement by means of a multi variable self-tuning controller.

It is another object of the invention to provide precise control of the thermal gradient eliminating the need for insulation.

It is yet another object of the invention to provide a controller that controls translation of the ampoule with respect to changes in the thermal dynamic conditions.

It is still another object of the invention to provide electro dynamic gradients with precise control and accounting for the zone to zone thermal interactions and thermal inertia of the ampoule.

It is a further object of the invention to provide smooth translation of the ampoule through the temperature zones.

It is yet a further object of the invention to have a computer based controller that models the thermal dynamic conditions within the furnace.

It is still a further object of the invention to provide power to the individual heating zones through a direct current source.

It is an additional further object of the invention to provide a transparent furnace for visual inspection of the ampoule.

It is yet an additional object of the present invention to optimally space heating elements within the furnace to allow good visual inspection of the interface.

It is still an additional further object of the invention to provide an educational tool allowing students to observe the effects on the crystal growth caused by changes in the temperature gradient within the furnace, translation of the ampoule, and disturbances to the ampoule as it passes through the furnace.

It is a further object of the invention to account for zone to zone thermal interaction and the thermal inertia of the ampoule.

The foregoing and other objects of the present invention, which shall become apparent as the detailed description proceeds, are achieved by a crystal growth system, comprising: a furnace; a plurality of heating elements coupled to said furnace, each said plurality of heating elements defining a heat zone, each said heating element set to a desired temperature value; a plurality of thermocouples associated with respective heat zones to detect a temperature value; a translation system for passing an ampoule containing crystal growth material through said furnace into said heat zones and providing a positional location of said ampoule and; a multi-variable self-tuning controller connected to said plurality of heating elements, said plurality of thermocouples and said translation system, said controller monitoring each said desired temperature value, each said heat zone temperature value and said positional location and upon considering the interaction of each, adjusting said desired temperature value to obtain optimal crystal growth within said ampoule.

Other objects of the present invention are obtained by a method for controlling the growth of a crystal in a crystal growth furnace comprising the steps of: providing a furnace with a substantially transparent inner tube having a cavity therethrough and a plurality of separate heating elements wound thereabout, each said heating element defining a heat zone, said inner tube having coupled thereto a temperature thermocouple associated with each said heat zone, said inner tube thermally insulated by a substantially transparent outer tube; inserting an ampoule filled with a crystal growth material into said cavity; energizing each said heating element to obtain a predetermined temperature gradient in each said heat zone thereby melting the crystal growth material into a liquid; monitoring the temperature of each said heat zone via said temperature thermocouples; and adjusting each said heating element to a new setting based upon the monitored temperatures of all the other heat zones so that said temperature gradient around said ampoule allows growth of crystal material from said liquid.

In general, a crystal growth system includes a transparent furnace with multiple heating zones heated by individual heating elements and a multivariable self-tuning controller.

Preferred exemplary crystal growth furnace incorporating the concepts of the present invention is shown by way of

example in the accompanying drawings without attempting to show all the various forms and modifications in which the invention might be embodied, the invention being measured by the appended claims and not by the details of the specification.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a diagram of a furnace and attached controller according to the present invention;

FIG. 1A is a schematic of the furnace;

FIG. 2 is a front elevational view of the furnace;

FIG. 3 is a cross-sectional view of the furnace;

FIG. 4 is an enlarged view of a furnace inner tube;

FIG. 4A is an enlarged view of a thermocouple attachment;

FIG. 5 is a block diagram of the control process;

FIG. 6 is a graph of the non-linear thermal profile used for crystal growth by a physical vapor transport; and,

FIG. 7 is an illustration of the multiple gradient capability with isothermal region.

DESCRIPTION OF AN EXEMPLARY EMBODIMENT

A crystal growth system made in accordance with the concepts of the present invention is indicated generally by the numeral 10 in the accompanying drawings. An example of the crystal growth furnace and controls is contained in Duval, Batur, and Bennett, *The Design of a Transparent Vertical Multi-Zone Furnace: Application to Crystal Growth*, NASA/TM 1998—207—412, incorporated by reference herein as if printed in its entirety. As shown in FIG. 1, the crystal growth system includes a tubular furnace 12 and a control system 14, a power source 16 and translation control system 40.

The furnace 12 includes an inner tube 20 having a cavity 21. An outer tube 22, which typically has the same structural properties as the inner tube 20, surrounds and encloses the inner tube 20. The inner tube 20 carries multiple heating elements 24 defining respective heat zones 26. In particular, each heating element 24 is associated with a particular heat zone 26, wherein an alphabetic suffix defines the relationship therebetween. Other suffix designators will be utilized to further define the relationship associated with each heat zone. As such, the heating element 24a generates a desired temperature in heat zone 26a. Likewise, each heating element 24 is connected to a corresponding power amplifier 28 to increase or decrease the temperature generated about its corresponding heat zone. As best shown in FIGS. 4 and 4A, temperature thermocouples 30 are coupled to an exterior surface of the inner tube 20 at about the mid-point 32 of each respective heating zone 26. Each thermocouple 30 measures the temperature generated in the corresponding heat zone and relays its heat zone temperature value to the control system 14. The outer tube 22 provides a plurality of port holes 31 in predetermined positions to allow ingress and egress of the heating elements 24 and the lead wires associated with each thermocouple 30. In the preferred embodiment, the thermocouple 30 is a K-type thermocouple with a bead diameter of about 0.5 mm.

The control system 14, which receives electrical power from a power source (not shown), includes a microprocessor 33 that contains the necessary hardware, software and memory to control the various operational aspects of the system 10. One of ordinary skill will appreciate that the

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individual components of the system can receive power from a variety of sources, including AC power supplies and DC power supplies. As will be discussed in further detail, the control system 14 determines the power to each heating element 24 and the resulting temperature measured by the thermocouples 30 to ensure the manufacture of a crystal with minimal thermal stresses evidenced by a substantially flat interface between the liquid and the crystal during its growth.

The crystal growth process involves lowering an ampoule 34 which initially contains a mixture of material components into the cavity 21 for the purpose of changing the components into the desired crystal material. Movement of the ampoule 34 is controlled by the translation control system 40. One end of the ampoule 34 is connected to a thin wire 36 which passes over a pulley 38. The other end of the thin wire 36 is connected to a DC motor with a harmonic gear based speed reducer system and translation controller 40. The translation controller 40 is connected to the microprocessor 33 and to the DC power source 16. The translation controller 40 provides smooth gradual and continuous movement of the ampoule 34 through the various heat zones at a predetermined rate of speed. Use of the translation controller 40 is particularly advantageous in that it provides very minimal disruption of the heat gradient within the cavity 21.

The controller 33 monitors the system 10 by sampling the position of the ampoule 34, the power to each heating element 24, and the temperatures as measured by each thermocouple 30. The controller coordinates operation of the entire system by multi-variable, self-tuning control as will be described in more detail below.

With reference to FIGS. 2 and 3, the inner tube 20 has a diameter of preferably about 46 mm and an inner tube wall thickness of preferably about 0.3 cm. The length of both the inner tube 20 and outer tube 22 is preferably about 52 cm. The outer tube 22 has an outer diameter of preferably about 68 mm with an inner diameter of about 64 mm. The outer tube 22 is in two sections 22a and 22b, divided along a split 41. The outer tube 22 is split into two sections to allow easy maintenance of the furnace components, such as the heating elements 24 and the temperature thermocouples 30. The outer tube 22 also functions as an insulator to maintain the desired heat distribution in the cavity 21 during the growth process and to also shield the inner tube 20 from extraneous influences.

A helical groove 44 of constant pitch is ground into an outer surface of the inner tube 20. The groove diameter is about 0.127 cm. The helical groove carries and supports each of the heating elements 24. Using a groove with a constant pitch allows for nearly uniform heat flux azimuthally. The pitch of the groove is optimized for visibility of the interface and to constrain movement of the heating elements.

As shown in FIG. 4A, blind holes 46 are drilled into the exterior surface of the inner tube 20 and do not pass all the way through the inner tube. They are merely drilled in the surface of the inner tube 20. The blind holes reduce heat loss that results from a through hole, and allow easy application and removal of thermocouples without disturbing the inside of the furnace. The holes are placed at about the midpoint of each heating zone 26, and at a position at an approximate midpoint between two adjacent heating element grooves 44. The temperature thermocouples 30 are inserted into respective blind holes 46 and held in place by an adhesive material or cement 74 that can withstand the high temperatures of the

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furnace. Each temperature thermocouple 30 measures the heat flux in a uniform manner at each heat zone.

As shown in the drawings, a plurality of thermocouple wire holes 47 are drilled through one section of the outer tube 22 on a line about 15 degrees from the split 41. In the exemplary device, these holes correspond to and are aligned with the thermocouple blind holes 46. Measuring from the top of the outer tube, the holes are at about 4 cm, 12 cm, 18.5 cm, 23.5 cm, 28.5 cm, 32.5 cm, 40 cm, and 48 cm. Opposite the thermocouple wire holes are safety thermocouple wire holes 50 with a diameter of about 1.6 mm and are located on a line 15 degrees from the side of the split 41. From the top 54, they are located at about 12 cm, 23.5 cm, 28.5 cm, and 40 cm. The purpose of the safety thermocouple wire holes 50 is discussed below. The outer tube 22 contains heating wire holes 48 of diameter of about 6.25 mm, and are located along the split 41 on one side of the tube. From the top 54, the heating wire holes 48 are at about 0.5 cm, 8 cm, 16 cm, 21 cm, 26 cm, 31 cm, 36 cm, 44 cm, and 51.5 cm.

A top locating ring 56 and a bottom locating ring 58 cap the inner tube 20 and outer tube 22. Each ring defines a center hole 59 capable of receiving the ampoule 34. As best shown in FIG. 2, the top locating ring 56 contains an inner circular notch 60 and an outer circular notch 62 for receiving the inner tube edges 15 and outer tube edges 18, respectively. The bottom locating ring 58 is similarly circularly notched. Both rings are preferably constructed of boron nitride or like material.

Preferably eight heating elements 24 are consecutively wrapped within the groove 44. The preferred heating element is Kanthal wire. Before wrapping the wire into the groove, the heating element wires are pre-stressed to insure a tight fit and to help prevent sagging of the wires when in use. Kanthal wire was chosen in the preferred embodiment because of its low expansion within the temperature range of 25° C. to 750° C. It will be apparent to one of ordinary skill to substitute different types of wire for different temperature ranges in this furnace. Each heating element 24 has wire ends 64 that protrude through the heating holes 48, and are connected to the power source 16.

Referring to FIG. 1, it can be seen that the servo amplifiers 28 provide power to each corresponding heating element 24. The servo amplifiers 28 are powered by the DC power supply 16. The servo amplifiers 28 receive control signals from the microprocessor based process controller 33 via a digital to analog converter 68 in electrical communication with the amplifiers.

Referring back to FIG. 1A, each heating element 24 defines a corresponding heat zone 26. Zone 1 is about 75 mm, zone 2 is about 80 mm, zone 3 is about 50 mm, zone 4 is about 50 mm, zone 5 is about 50 mm, zone 6 is about 50 mm, zone 7 is about 80 mm, and zone 8 is about 75 mm. Zone lengths are optimized to achieve temperature ranges of 25° C. to 750° C. and thermal gradients of about 2° C. per cm through 45° C. per cm. It will be appreciated that the zone lengths may be modified to suit other crystal materials and their associated temperature ranges. Zone lengths are more compact near the interface point, which is the area in the cavity 21 where the liquid material converts into a crystal. More compact zones are used to achieve greater control of the thermal gradient and thus better control over the interface shape. The thermocouples 30 have beads 70 with a diameter of about 0.5 mm. The thermocouples 30 are attached to the inner tube 20 in their respective blind holes 46. Each thermocouple 30 has a pair of wires 72 that pass through the temperature holes 47 to an analog to digital converter 74, which is connected to microprocessor 33.

Safety thermocouples **100** run through the safety thermocouple wire holes **50** in the outer tube. These thermocouples monitor the temperature in the furnace for safety purposes. Since, the furnace is operating for long periods of time without supervision, it is important that if the furnace malfunctions that it will be shut down immediately. The safety thermocouples monitor the temperature and are in communication with an independent safety on-off controller **110** that will shut down the furnace when temperature within the furnace exceeds a safety value.

The control system **14** regulates the crystal growth process. The microprocessor **33** implements a multi-variable self tuning controller. Multi-variable because it monitors the temperatures of eight heating zones **26** simultaneously and adjusts the voltages applied to eight heating zones simultaneously based on a thermal dynamic model of the furnace. Self-tuning because this multi-input multi-output thermal dynamic model of the furnace is automatically adjusted every sampling time that microprocessor **33** reads eight heating zone temperatures **26**. An algorithm within the microprocessor **33** uses a self-tuned, multi-variable proportional plus integral (PI) algorithm that is updated based on the thermal dynamic model of the furnace. This dynamic model is a mathematic expression that relates temperatures of all eight heating zones to voltage input to all eight heating zones. Thermal interactions among heating zones are explicitly accounted for in this mathematical model. We use the following dynamic model of the furnace for the purpose of controller design.

$$T(t)=A.T(t-1)+B.u(t-1)+e(t)$$

Where  $u(t)$  and  $T(t)$  are vectors of dimension eight for an eight zone furnace i.e.,  $u, T \in \mathbb{R}^{8 \times 1}$ . The vector  $u(t)$  indicates eight voltage levels at time (t) as the inputs to the servo amplifiers **28**. These inputs are determined by the multi-variable projective control based PI control algorithm. The vector  $T(t)$  denotes the measured zone temperatures. The disturbance vector  $e(t) \in \mathbb{R}^8$  indicates the inevitable zone to zone thermal interactions and the effect of thermal loading. The matrices  $A, B \in \mathbb{R}^{8 \times 8}$  define the thermal dynamics of the system. The process input, determined by the temperature controller, is the voltage input into eight heating zones, i.e.,  $u=(u_1, u_2, \dots, u_8)^T$ .

As shown in FIG. **5**, the microprocessor **33** periodically samples the temperature of eight zones simultaneously. These temperatures are detected by the thermocouples **30**. The sampling period is normally 0.5 second but it can be adjusted by the programmer. Based on the sampled heating zone temperatures, the microprocessor **33** updates the thermal model. Updating means that the matrix coefficients in this mathematical model are determined at each sampling instant in order to update the thermal model that best represents the current sampled temperatures in the least squares sense. The model updating is based on the multi-variable Least Squares criterion, i.e., at each sampling instant the model matrices  $A$  and  $B$  are updated such that the sum of squares of the residuals are minimum, i.e., the following identification performance index is minimum

$$V_{ID} = \text{trace} \left\{ \arg_{\hat{A}, \hat{B}} \text{minimum of} \left[ \sum_{k=1}^t \hat{e}(k) \cdot \hat{e}^T(k) \right] \right\}$$

where the residual of the model is given by

$$\hat{e}(k)=T(k)-\hat{A}.T(k-1)-\hat{B}.u(k-1)$$

After the update, the difference between the measured heating zone temperatures and the temperatures predicted by

the thermal model is minimum in a least squares sense. Once the thermal model is updated, the parameters of the PI controller are modified to take into account the most recent model of the furnace thermal dynamics. Modification of the PI control parameters is based on the linear quadratic regulator design whereby the matrices of the PI regulator are determined such that the controller minimizes a specific performance index. Where the index is given by:

$$PI = \sum_{k=t}^{\infty} \{ [r(k) - T(k)]^T Q [r(k) - T(k)] + u^T(k) R u(k) \}$$

This index is a function of the difference between the desired temperatures in all heating zones and the actual temperatures of all heating zones. In addition, this index also contains a term  $u(k)$  which indicates the energy input to all heating zones. Where the term  $u(k)$  is given by:

$$u(k) = K_1 [r(k) - T(k)] + K_2 \sum_{k=-\infty}^{k=t} [r(k) - T(k)]$$

Therefore, when this index is minimized, the deviations from the desired temperatures are minimized while taking into account the energy input to heating zones. It is not a good engineering practice to minimize the deviations at the expense of very large energy inputs to heating zones. The minimization of this index determines the matrices of the PI regulator. This index is minimized at every sampling period. Therefore, the matrices of PI regulator are determined at every sampling period. Modification of the PI regulator matrices allows the fastest corrective response to thermal disturbances without causing overshoot or undershoot in the zone temperatures. These thermal disturbances are the inevitable zone to zone heat exchange and the thermal inertia of the material inside the ampoule. The PI controller determines the input voltages to the servo amplifiers **28** based on the updated matrices.

Control of the individual heat zones also allows translation of the thermal gradient by changing the set-point temperatures of each zone with respect to time. This type of control can be used to perform a method of crystal growth known as electro dynamic gradient or EDG. Without moving the ampoule physically through the furnace, the temperature of the heat zones are moved around the ampoule by changing the set point temperatures. In other words, the thermal gradient is moved electronically. The self-tuning multi-variable furnace temperature controller can perform EDG by changing the set point temperatures in the individual zones and accounting for inevitable zone to zone interactions caused by heat flows among the zones.

As shown in FIG. **6**, the self-tuning multi-variable temperature controller can generate thermal gradients which are suitable for the physical vapor transport crystal growth. On FIGS. **6** and **7**, zone numbers and set point temperatures appear along the top axis with lines indicating the start and end of each zone connected to the bottom axis. The data points represented by circles in FIG. **6** and a solid line in FIG. **7** are the temperature measured at the center of the inner tube **20**. Dashed lines in both FIGS. **6** and **7** are temperatures measured along the periphery of the inner tube. Temperature measurements were taken locations along the Z axis.

As shown in FIG. **7**, the controller can maintain multiple gradients in the furnace **12**. The microprocessor **33** can account for zone to zone thermal interaction and respond by

controlling the translation of the ampoule 34 or by changing the temperature in each heating zone 26 thereby adjusting the thermal profile within the furnace.

It should thus be evident that a crystal furnace made in accordance with the concepts of the present invention accomplishes the objects of the present invention and otherwise substantially improves the crystal growth furnace art.

What is claimed is:

1. A method for controlling the growth of a crystal in a crystal growth furnace comprising the steps of:

providing a furnace with a substantially transparent inner tube having a cavity therethrough and a plurality of separate heating elements wound thereabout, each said heating element defining a heat zone, said inner tube having coupled thereto a temperature thermocouple associated with each said heat zone, said inner tube insulated by a substantially transparent outer tube;

inserting an ampoule filled with a crystal growth material into said cavity;

energizing each said heating element to obtain a predetermined temperature gradient in the furnace thereby melting the crystal growth material into a liquid;

monitoring the temperature of each said heat zone via said temperature thermocouples; and

adjusting voltage input to a said heating element to a new setting based upon the monitored temperatures of all the other heat zones so that said temperature gradient around said ampoule allows growth of crystal material from said liquid.

2. The method according to claim 1, wherein said ampoule is substantially transparent and the method further comprises the steps of:

visually observing the growth of the crystal through said outer tube, said inner tube and said ampoule to determine whether a substantially flat surface is being obtained; and

adjusting a thermal profile in the furnace if said flat interface is not obtained.

3. The method according to claim 2, further comprising the steps of:

translating said ampoule through said cavity at a predetermined rate with a DC motor; and

adjusting each said heating element to a new temperature setting based upon the monitored temperatures of all of the other heat zones and a translation rate of said ampoule.

4. The method according to claim 2, further comprising the step of:

providing a microprocessor with a mathematical model of furnace thermal dynamics of how said heat zones should be energized;

interconnecting said heating elements, said temperature thermocouples and said motor to said microprocessor which monitors the temperatures and adjusts the voltage input to each heater accordingly.

5. A method of controlling temperature within a crystal growth furnace having a plurality of heating elements, each heating element defining a zone, and a temperature sensor associated with each zone, the method comprising:

providing a microprocessor with a mathematical model of the furnace thermal dynamics; and

interconnecting the heating elements and temperature sensors to the microprocessor which monitors the temperature and adjusts the voltage input to each heating element accordingly.

6. The method of claim 5, further comprising periodically monitoring the temperatures and voltage in each zone; and updating the mathematical model at each monitoring.

7. The method of claim 6, wherein updating includes using the temperature and voltage from the previous monitoring to minimize the difference between the measured heating zone temperatures and temperatures predicted by the mathematical model.

8. The method of claim 6 wherein updating is based on a multi-variable least squares criterion.

9. The method of claim 6, further comprising after updating the mathematical model, modifying control parameters used to apply voltage to the heating elements.

10. The method of claim 6, wherein the mathematical model is represented by

$$T(k)=A.T(k-1)+B.u(k-1)+e(k)$$

where T(k) represents the temperature for each zone at a present time, where T(k-1) represents the temperature at a previous time, where u(k-1) represents the voltage for each zone at the previous time, wherein A and B are matrices identifying the thermal dynamics of the furnace and wherein e(k) is a residual value, which signifies the modeling error.

11. The method of claim 10, wherein matrices A and B are updated such that the sum of the squares of the residual are minimum.

12. The method of claim 11, wherein the sum of the squares is minimized according to the equation:

$$V_{ID} = \text{trace} \left\{ \arg_{\hat{A}, \hat{B}} \text{minimum of} \left[ \sum_{k=1}^t \hat{e}(k) \cdot \hat{e}^T(k) \right] \right\}$$

wherein residual  $\hat{e}(k)$  is represented by the equation:

$$\hat{e}(k)=T(k)-\hat{A}.T(k-1)-\hat{B}.u(k-1)$$

wherein t is current time and k is a sampling interval index.

13. The method of claim 12, wherein updating parameters of the self-tuning controller includes minimizing a performance index to determine the parameters.

14. The method of claim 13, wherein the performance index is for a linear quadratic regulator and is represented by the equation:

$$PI = \sum_{k=t}^{\infty} \{ [r(k) - T(k)]^T Q [r(k) - T(k)] + u^T(k) R u(k) \}$$

wherein u(k) is the control signal for a proportional integral controller for the time index k, said control signal being represented by:

$$u(k) = K_1 [r(k) - T(k)] + K_2 \sum_{k=-\infty}^{k=t} [r(k) - T(k)]$$

where r(k) represents the desired temperature in all heating zones, and wherein T(k) is represented by:

$$T(k)=\hat{A}T(k-1)+\hat{B}u(k-1)$$

where k-1 is the previous time index and  $\hat{A}$  and  $\hat{B}$  are current model parameters.

15. A method of controlling temperature within a crystal growth furnace having a plurality of heating elements, each heating element defining a zone, and a temperature sensor

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associated with each zone, and a moveable ampoule containing crystal material, the method comprising:  
providing a microprocessor with a mathematical model of the furnace thermal dynamics, wherein the microprocessor samples temperature within each zone and position of the ampoule;  
updating the mathematical model based on the sampled temperatures;

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updating parameters of a self-tuning controller based on the updated model of the furnace;  
determining the voltage input to the heating zones with the updated parameters; and  
adjusting the input voltage to the heating elements accordingly.

\* \* \* \* \*